

# Time Series Deconfounder: Estimating Treatment Effects over Time in the Presence of Hidden Confounders

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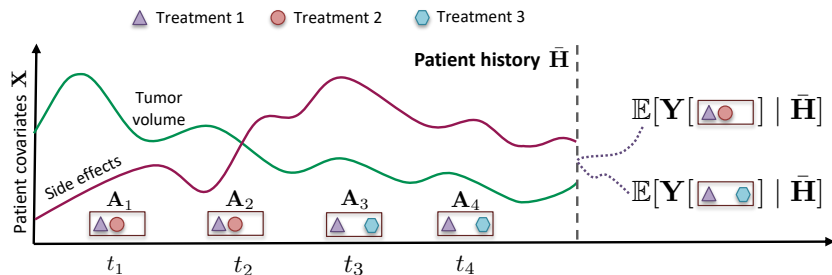


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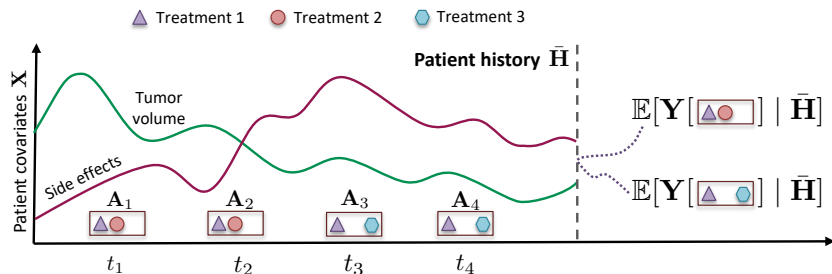
# Introduction

- Aim:** Estimate the individualized effects of time-dependent treatments.



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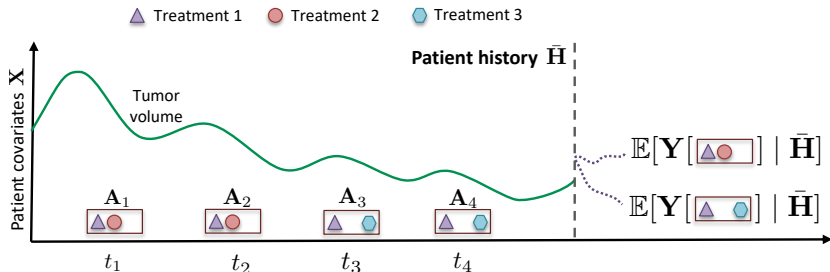
- **Aim:** Estimate the individualized effects of time-dependent treatments.



- All existing methods for estimating treatment effects over time assume that there are no hidden confounders.

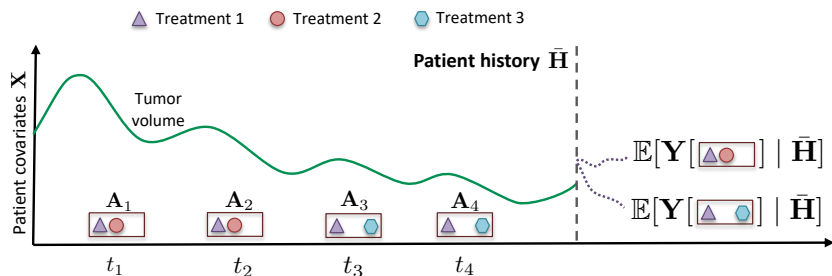
# Hidden confounders

- Hidden confounders introduce bias when estimating treatment effects over time.



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- Proposed solution:** infer latent variables that capture the dependencies in the treatment assignments over time and can be used as substitutes for the hidden confounders.

## Problem formalism

- Observational data for each patient:
  - ▶ Time-dependent patient covariates:

$$\bar{\mathbf{X}}_t = (\mathbf{X}_1, \dots, \mathbf{X}_t)$$

- ▶ Time-dependent treatments:

$$\bar{\mathbf{A}}_t = (\mathbf{A}_1, \dots, \mathbf{A}_t), \text{ where } \mathbf{A}_t = [A_{t1} \dots A_{tk}]$$

- ▶ Observed patient outcome given history of covariates  $\bar{\mathbf{X}}_t$  and treatments  $\bar{\mathbf{A}}_t$ :  $\mathbf{Y}_{t+1}$ .

## Potential outcomes

- Use the potential outcomes framework (Rubin (1978), Neyman (1923), Robins & Hernan (2008)).
- Estimate **individualized treatment effects**, i.e. potential outcomes under treatment plan  $\bar{\mathbf{a}}_{\geq t}$  conditional on patient history at timestep  $t$ :

$$\mathbb{E}[\mathbf{Y}(\bar{\mathbf{a}}_{\geq t}) \mid \bar{\mathbf{A}}_{t-1}, \bar{\mathbf{X}}_t]$$

- Assume consistency and positivity.

## Potential outcomes and hidden confounders

- Estimate individualized treatment effects, i.e. potential outcomes under treatment plan  $\bar{\mathbf{a}}_{\geq t}$  conditional on patient history at timestep  $t$ :

$$\mathbb{E}[\mathbf{Y}(\bar{\mathbf{a}}_{\geq t}) \mid \bar{\mathbf{A}}_{t-1}, \bar{\mathbf{X}}_t]$$

- All existing methods assume that there are **no hidden confounders**:

$$\mathbf{Y}(\bar{\mathbf{a}}_{\geq t}) \perp\!\!\!\perp \mathbf{A}_t \mid \bar{\mathbf{X}}_t, \bar{\mathbf{A}}_{t-1} \text{ for all } \bar{\mathbf{a}}_{\geq t} \text{ and for all } t,$$

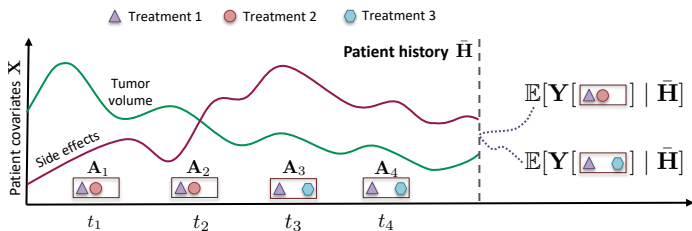
which is **untestable** in practice.



## Hidden confounders - from static to temporal setting

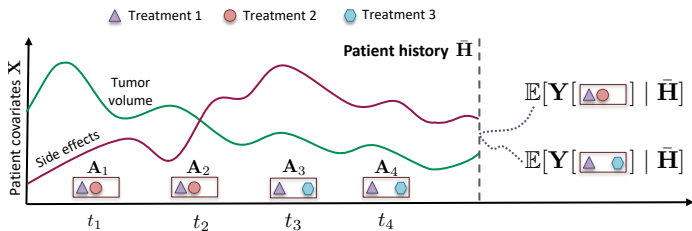
- The Blessing of Multiple Causes (Wang & Blei, 2019):
  - ▶ Static causal inference setting.
  - ▶ Hidden confounders introduce dependencies in the treatment assignments.
  - ▶ Infer latent variables that capture these dependencies and render the treatments conditionally independent.
- In the temporal setting, the hidden confounders may change over time and may be affected by past treatments and covariates.

# Time Series Deconfounder - Main ideas



- Hidden confounders may vary over time and may be affected by previous treatments and covariates.

# Time Series Deconfounder - Main ideas



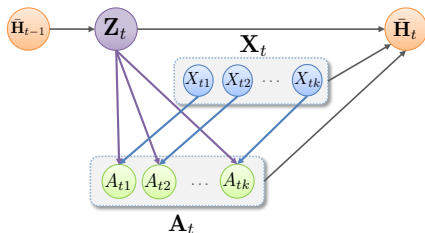
- Take advantage of the way multiple treatments are assigned over time to infer substitutes for the hidden confounders.

$$\bar{\mathbf{Z}}_t = (\mathbf{Z}_1, \dots, \mathbf{Z}_t)$$

- Augment the observational dataset with  $\bar{\mathbf{Z}}_t$  and use an outcome model to obtain unbiased estimates of the treatment effects.

# Time Series Deconfounder - Factor model

Step 1: Fit **factor model over time** to infer substitutes for the hidden confounders.

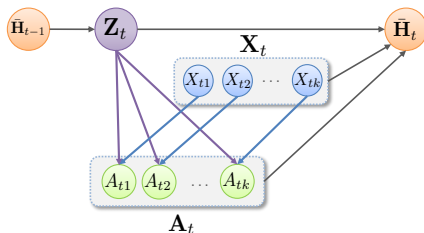


- At time  $t$  construct the **latent variable**  $\mathbf{Z}_t$  as a function of history  $\bar{\mathbf{H}}_{t-1} = (\bar{\mathbf{A}}_{t-1}, \bar{\mathbf{X}}_{t-1}, \bar{\mathbf{Z}}_{t-1})$ , such that:

$$p(A_{t1}, \dots, A_{tk} \mid \mathbf{Z}_t, \mathbf{X}_t) = \prod_{j=1}^k p(A_{tj} \mid \mathbf{Z}_t, \mathbf{X}_t).$$

# Time Series Deconfounder - Factor model

Step 1: Fit **factor model over time** to infer substitutes for the hidden confounders.

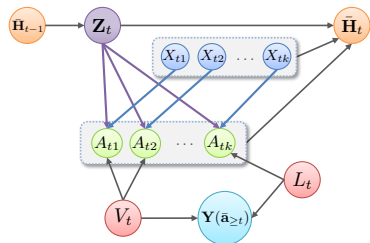
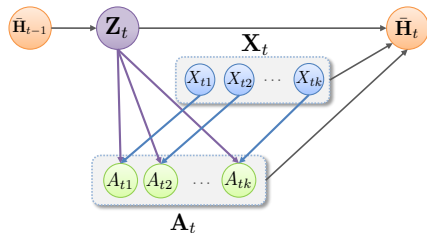


- Factor model of the assigned treatments has joint distribution:

$$p(\theta_{1:k}, \bar{\mathbf{x}}_T, \bar{\mathbf{z}}_T, \bar{\mathbf{a}}_T) = p(\theta_{1:k})p(\bar{\mathbf{x}}_T).$$

$$\prod_{t=1}^T (p(\mathbf{z}_t | \bar{\mathbf{h}}_{t-1}) \prod_{j=1}^k p(a_{tj} | \mathbf{z}_t, \mathbf{x}_t, \theta_j)).$$

# Time Series Deconfounder - Factor model



Assumption (Sequential single strong ignorability)

$$Y(\bar{a}_{\geq t}) \perp\!\!\!\perp A_{tj} \mid \mathbf{X}_t, \bar{H}_{t-1},$$

$\forall \bar{a}_{\geq t}$  and  $\forall t \in \{0, \dots, T\}$  and  $\forall j \in \{1, \dots, k\}$ .

# Time Series Deconfounder - Sequential strong ignorability

## Theorem

*If the distribution of the assigned causes  $p(\bar{\mathbf{a}}_T)$  can be written as the factor model  $p(\theta_{1:k}, \bar{\mathbf{x}}_T, \bar{\mathbf{z}}_T, \bar{\mathbf{a}}_T)$ , we obtain sequential ignorable treatment assignment:*

$$\mathbf{Y}(\bar{\mathbf{a}}_{\geq t}) \perp\!\!\!\perp (A_{t1}, \dots, A_{tk}) \mid \bar{\mathbf{A}}_{t-1}, \bar{\mathbf{X}}_t, \bar{\mathbf{Z}}_t,$$

*for all  $\bar{\mathbf{a}}_{\geq t}$  and for all  $t \in \{0, \dots, T\}$ .*

## Evaluate factor model

- Use predictive checks (Rubin, 1984) to assess how well the factor model captures the distribution of treatments at each timestep.
- The inferred substitutes for the hidden confounders  $\mathbf{Z}_t$  also need to satisfy positivity, i.e.

$$P(\mathbf{A}_t = \mathbf{a}_t \mid \bar{\mathbf{A}}_{t-1} = \bar{\mathbf{a}}_{t-1}, \bar{\mathbf{Z}}_t = \bar{\mathbf{z}}_t, \bar{\mathbf{X}}_t = \bar{\mathbf{x}}_t) > 0.$$



## Time Series Deconfounder - Outcome model

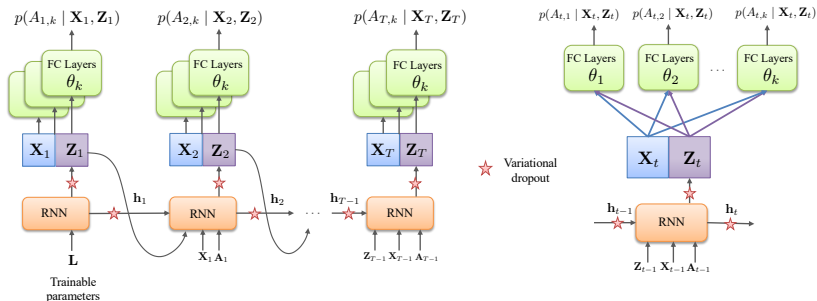
**Step 2:** Sample  $\hat{\mathbf{Z}}_t = [\hat{\mathbf{Z}}_1 \dots \hat{\mathbf{Z}}_t]$  from the factor model and fit an outcome model to estimate:

$$\mathbb{E}[\mathbf{Y} \mid \bar{\mathbf{a}}_{\geq t}, \bar{\mathbf{A}}_{t-1}, \bar{\mathbf{X}}_t, \hat{\mathbf{Z}}_t] = \mathbb{E}[\mathbf{Y}(\bar{\mathbf{a}}_{\geq t}) \mid \bar{\mathbf{A}}_{t-1}, \bar{\mathbf{X}}_t, \hat{\mathbf{Z}}_t].$$

Example outcome models: *Marginal Structural Models* (Robins et al. 2000), *Recurrent Marginal Structural Networks* (Lim et al., 2018).

# Proposed factor model architecture

- Proposed architecture for the factor model: recurrent neural network (RNN) with **multitask output** and **variational dropout**.



$$\mathbf{Z}_1 = \text{RNN}(\mathbf{L})$$

$$\mathbf{Z}_t = \text{RNN}(\bar{\mathbf{Z}}_{t-1}, \bar{\mathbf{X}}_{t-1}, \bar{\mathbf{A}}_{t-1}, \mathbf{L})$$

$$A_{tj} = \text{FC}(\mathbf{X}_t, \mathbf{Z}_t; \theta_j), \text{ for all } j = 1, \dots, k$$

## Experiments on synthetic data

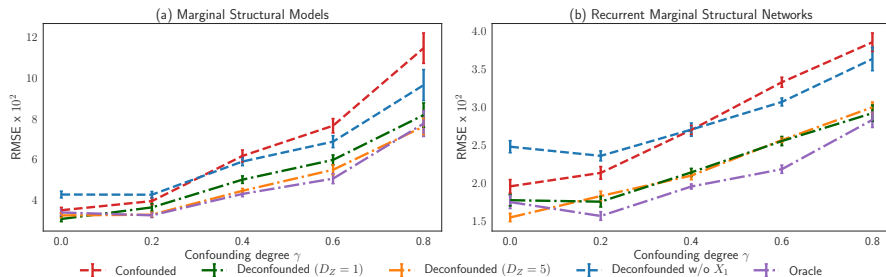
Build synthetic dataset using  $p$ -order autoregressive processes:

$$X_{t,j} = \frac{1}{p} \sum_{i=1}^p (\alpha_{i,j} X_{t-i,j} + \omega_{i,j} A_{t-i,j}) + \eta_t,$$
$$Z_t = \frac{1}{p} \sum_{i=1}^p (\beta_i Z_{t-i} + \sum_{j=1}^k \lambda_{i,j} A_{t-i,j}) + \epsilon_t,$$

$$\pi_{tj} = \gamma_A \hat{Z}_t + (1 - \gamma_A) \hat{X}_{tj}, \quad A_{tj} \mid \pi_{tj} \sim \text{Bernoulli}(\sigma(\lambda \pi_{tj})),$$

$$\mathbf{Y}_{t+1} = \gamma_Y Z_{t+1} + (1 - \gamma_Y) \left( \frac{1}{k} \sum_{j=1}^k X_{t+1,j} \right).$$

# Experiments on synthetic data



- Root mean squared error (RMSE) obtained for one-step ahead estimation of treatment effects.
- The parameters  $\gamma = \gamma_A = \gamma_Y$  control the amount of hidden confounding.

## Experiments on MIMIC III

- Dataset with 6256 patients, with 25 covariates (lab tests and vital signs) per person and trajectories up to 50 days.
- Estimate the effect of antibiotics, vassopressors and mechanical ventilator on patient covariates.
- Hidden confounding is present in the dataset as patient comorbidities and several lab tests were not included.

Outcome model	White blood cell count		Blood pressure		Oxygen saturation	
	MSM	R-MSN	MSM	R-MSN	MSM	R-MSN
Confounded	$3.90 \pm 0.00$	$2.91 \pm 0.05$	$12.04 \pm 0.00$	$10.29 \pm 0.05$	$2.92 \pm 0.00$	$1.74 \pm 0.03$
$D_Z = 1$	$3.55 \pm 0.05$	$2.62 \pm 0.07$	$11.69 \pm 0.14$	$9.35 \pm 0.11$	$2.42 \pm 0.02$	$1.24 \pm 0.05$
$D_Z = 5$	$3.56 \pm 0.04$	$2.41 \pm 0.04$	$11.63 \pm 0.10$	$9.45 \pm 0.10$	$2.43 \pm 0.02$	$1.21 \pm 0.07$
$D_Z = 10$	$3.58 \pm 0.03$	$2.48 \pm 0.06$	$11.66 \pm 0.14$	$9.20 \pm 0.12$	$2.42 \pm 0.01$	$1.17 \pm 0.06$
$D_Z = 20$	$3.54 \pm 0.04$	$2.55 \pm 0.05$	$11.57 \pm 0.12$	$9.63 \pm 0.14$	$2.40 \pm 0.01$	$1.28 \pm 0.08$

## Discussion and limitations

- The Time Series Deconfounder enables the estimation of treatment effects over time using weaker assumptions than existing methods.
- Identifiability of the potential outcomes using the deconfounder framework may represent an issue:
  - ▶ non-identifiability will be indicated by the high variance of the estimated outcomes.

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